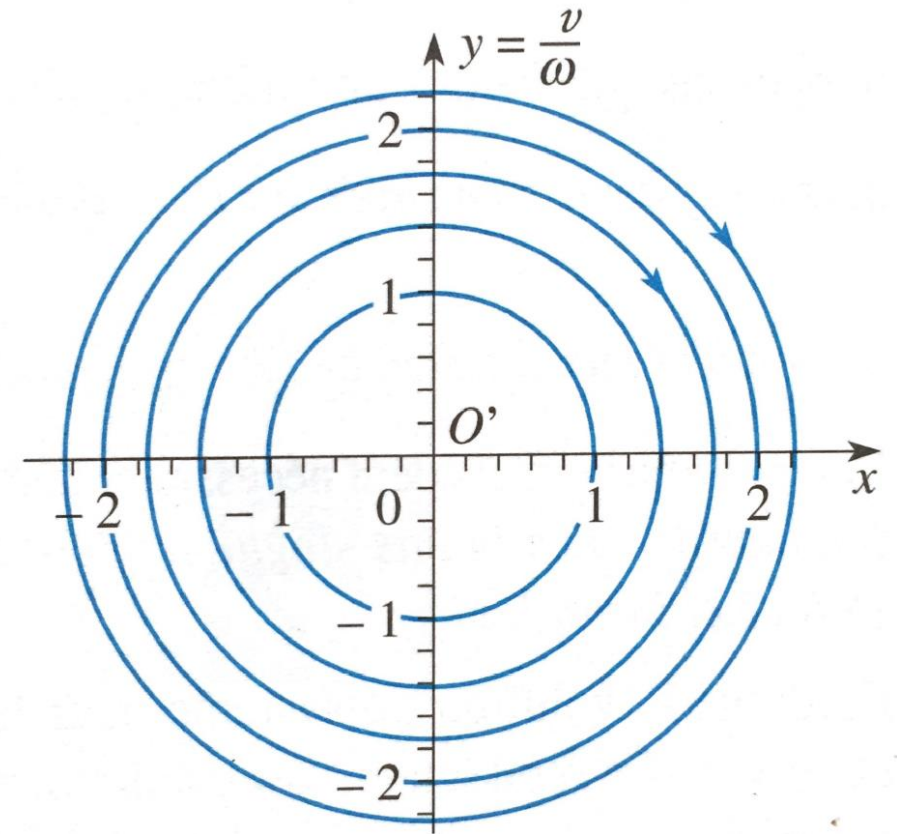
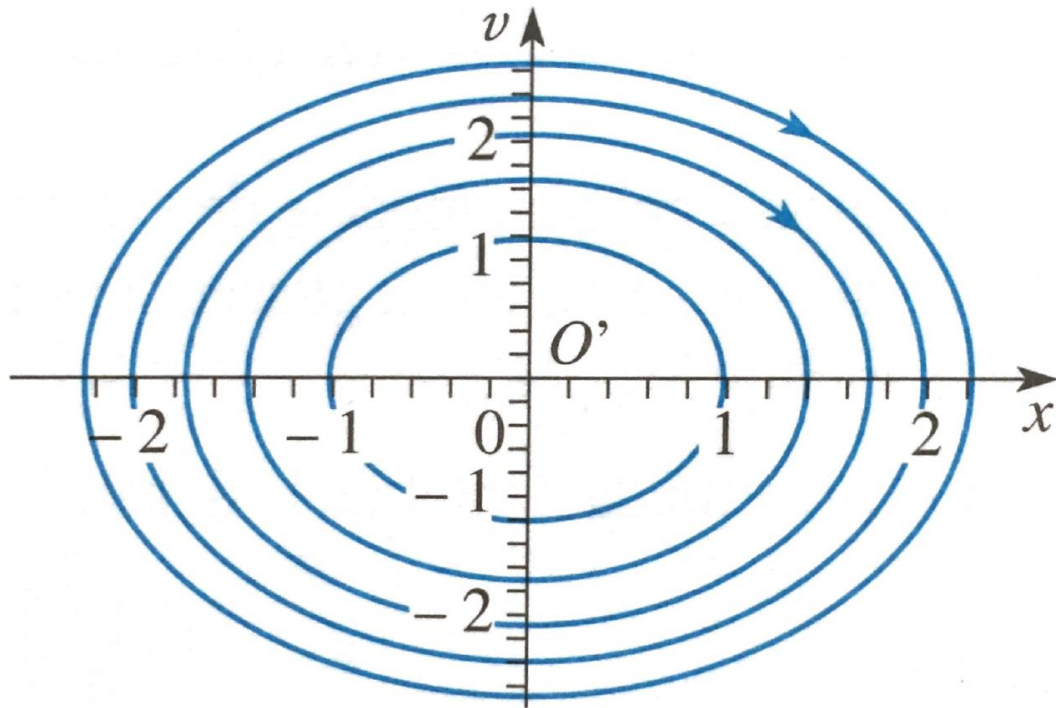


# L.P. 49 – Oscillateurs ; portraits de phase et non- linéarité

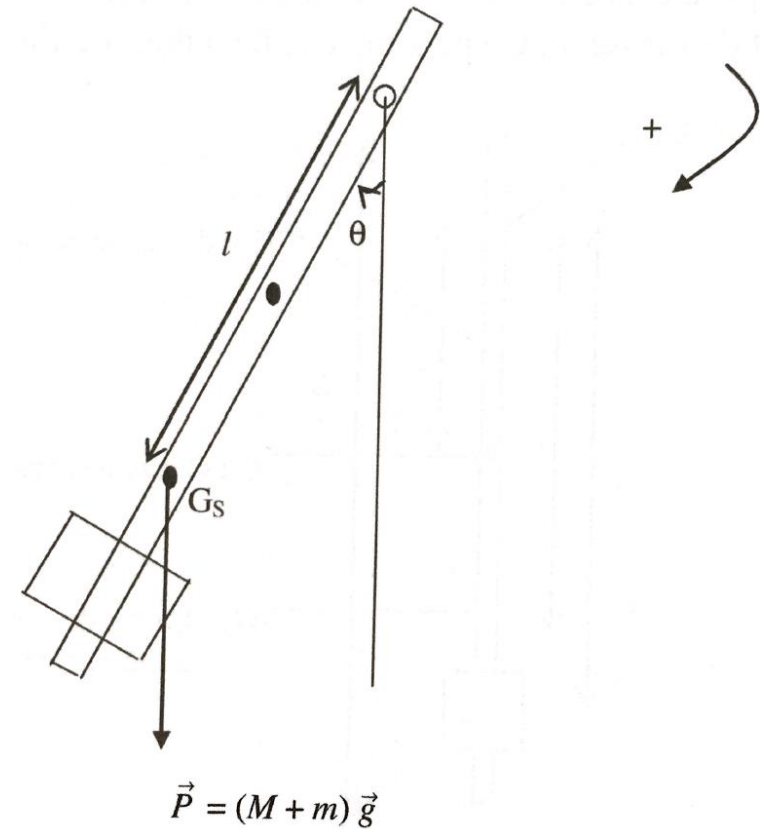
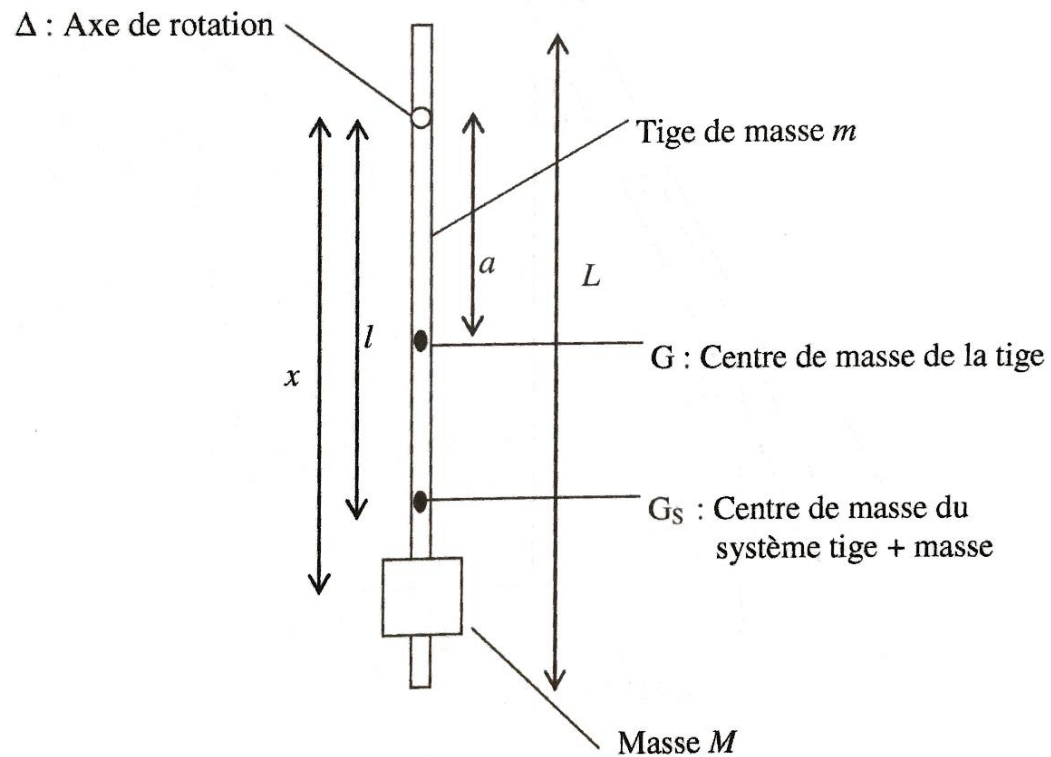
Marchetti Benjamin

# 1. L'oscillateur non amorti L'oscillateur harmonique



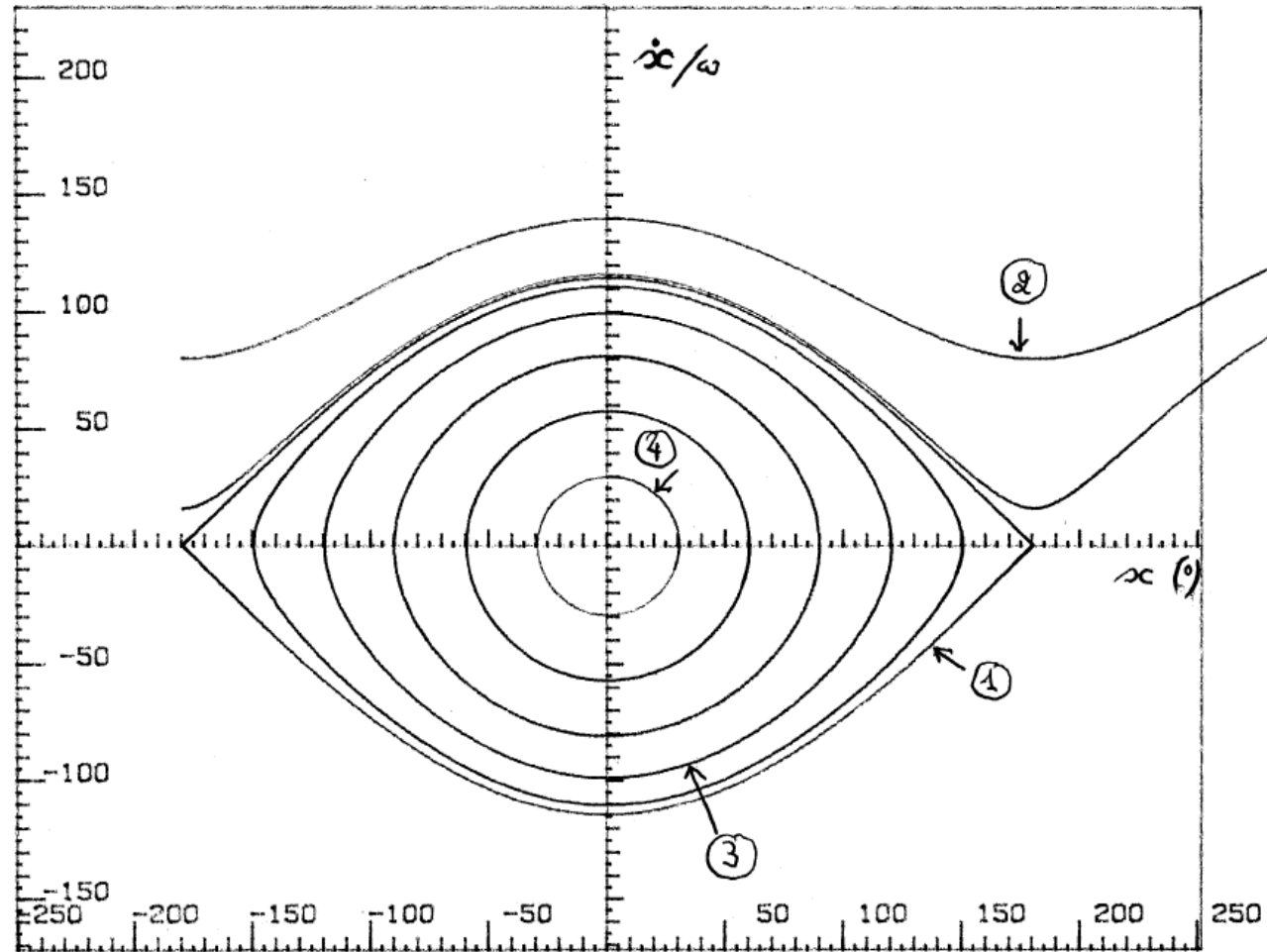
# 1. L'oscillateur non amorti

## Le pendule pesant



# 1. L'oscillateur non amorti

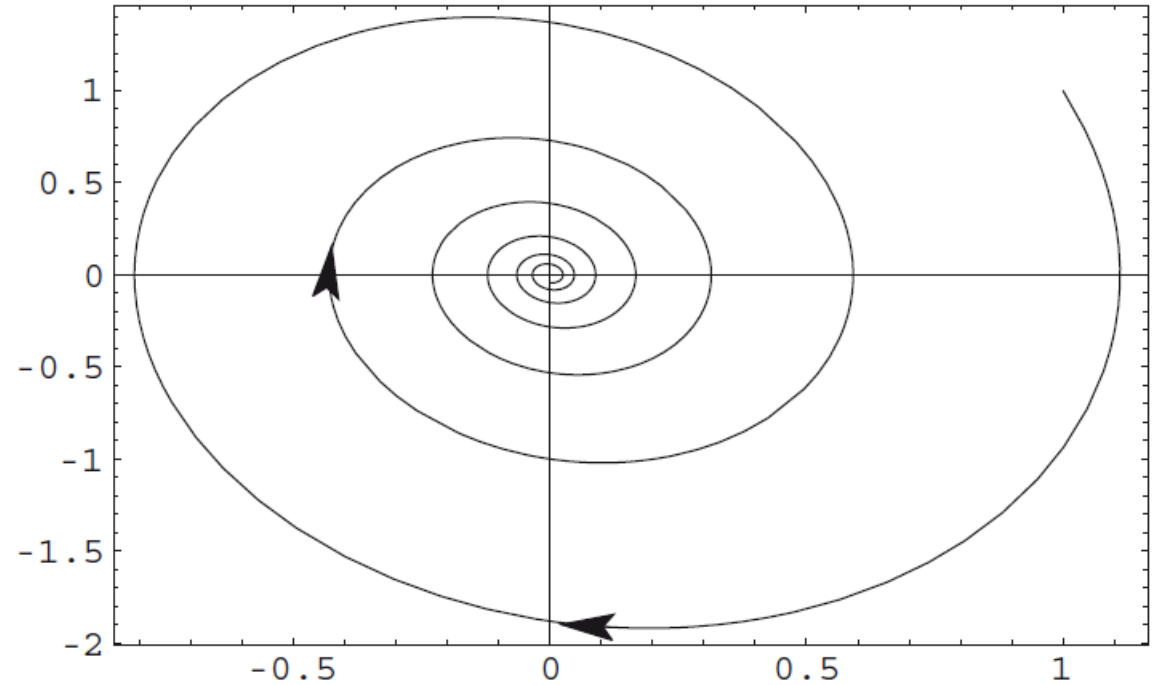
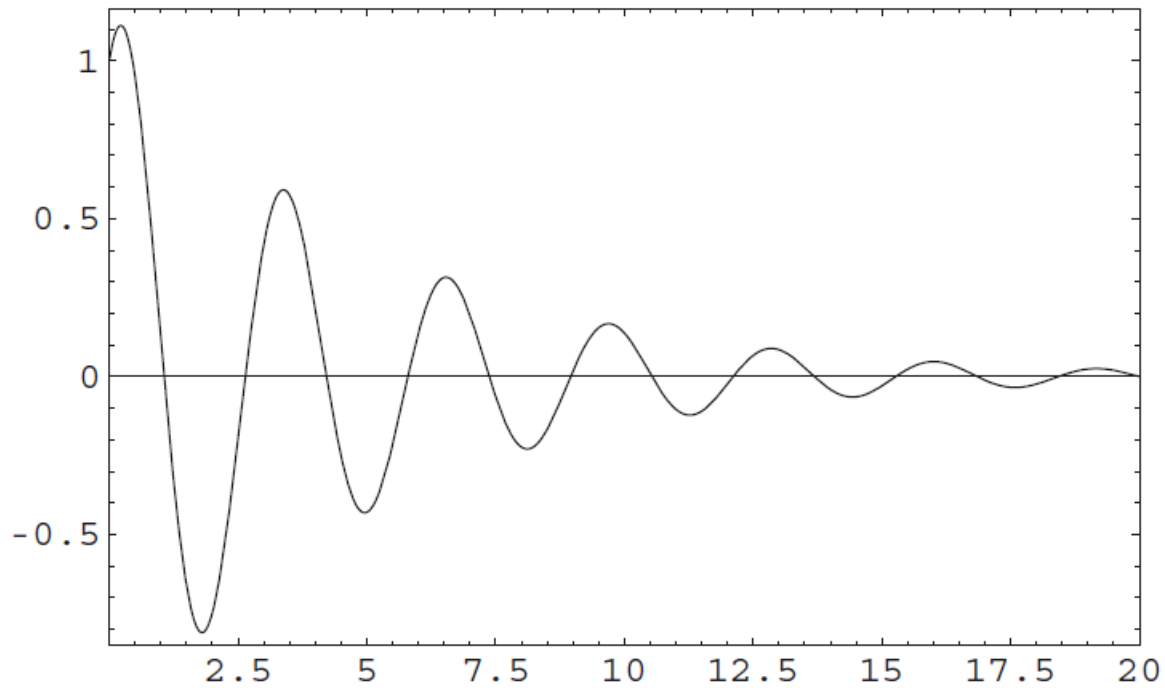
## Le pendule pesant



## 2. L'oscillateur amorti

L'oscillateur harmonique amorti (par frottement fluide)

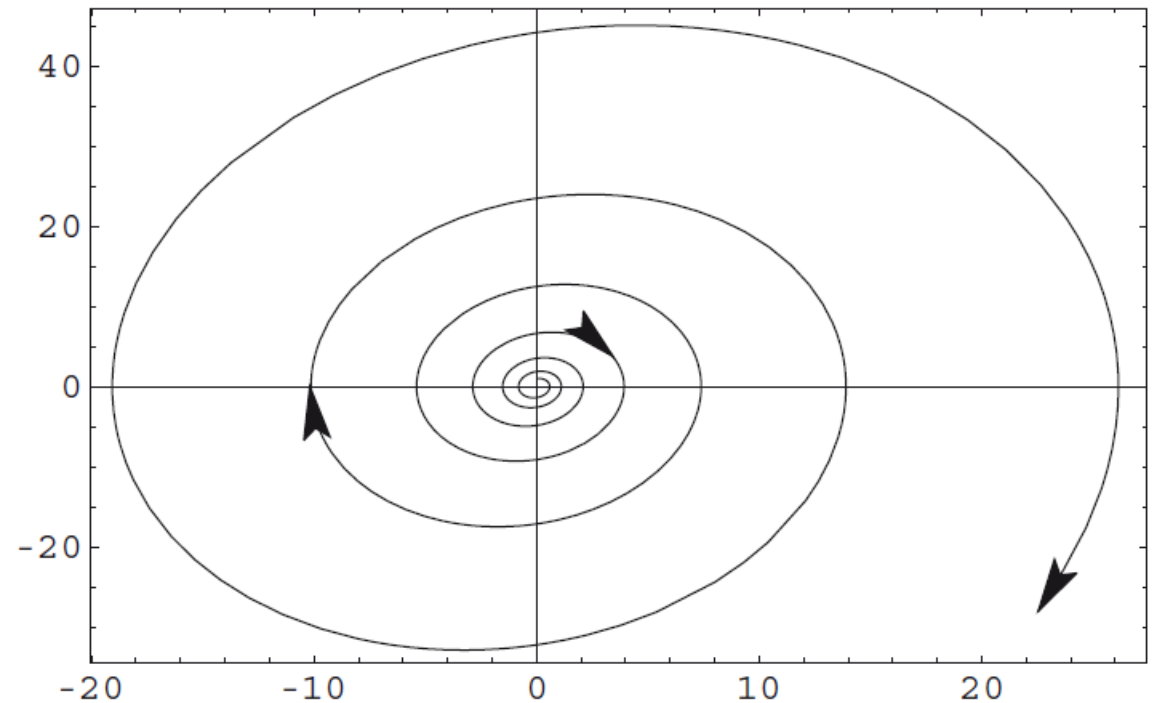
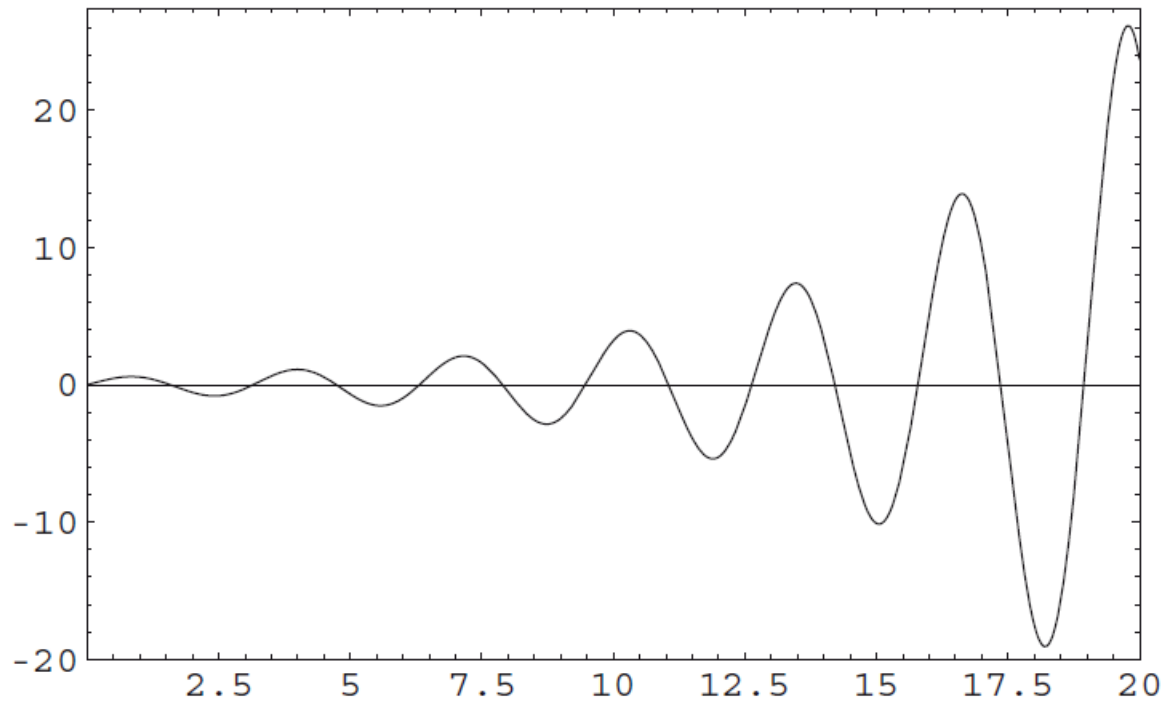
$$\xi > 0$$



## 2. L'oscillateur amorti

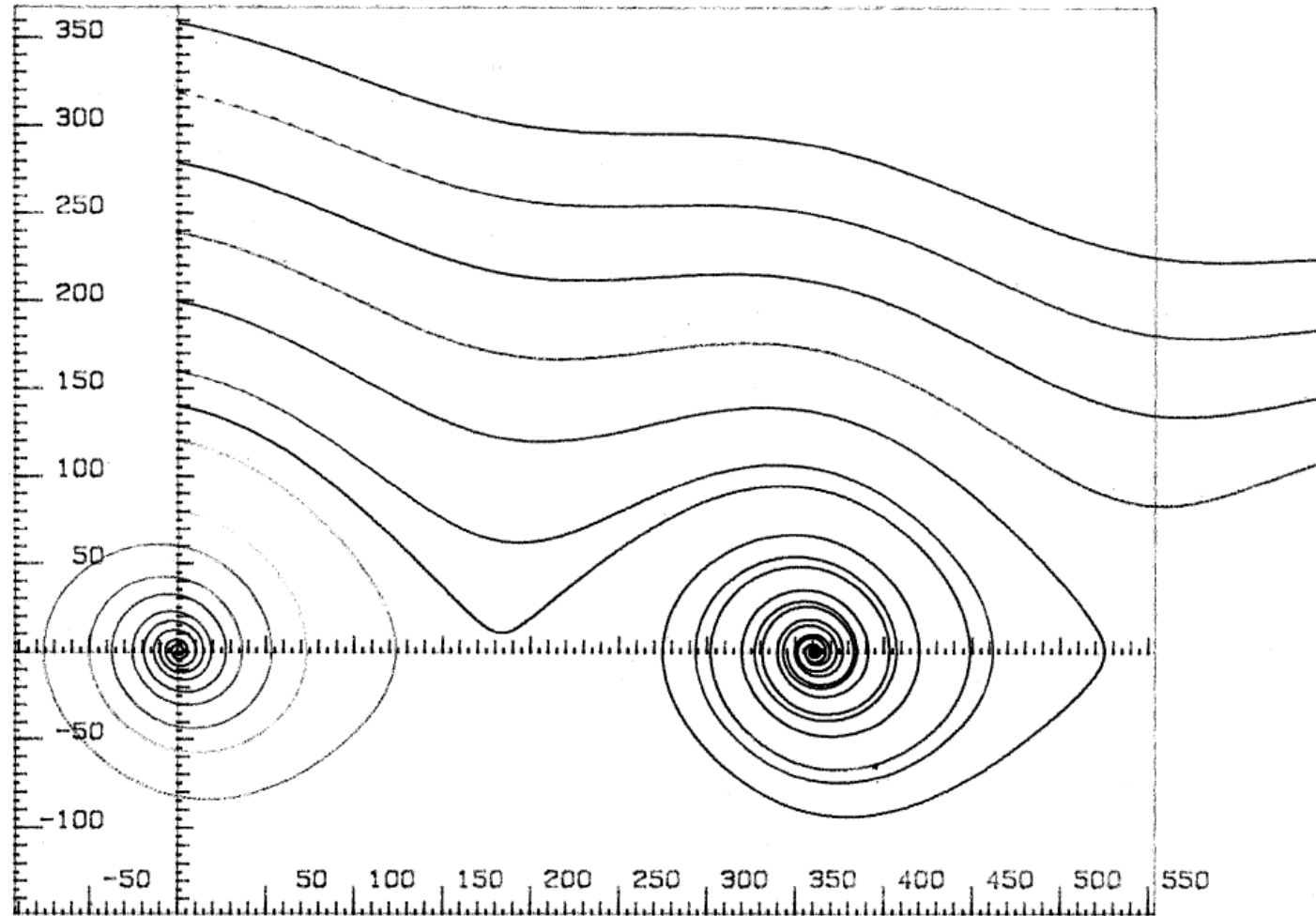
L'oscillateur harmonique amorti (par frottement fluide)

$$\xi < 0$$

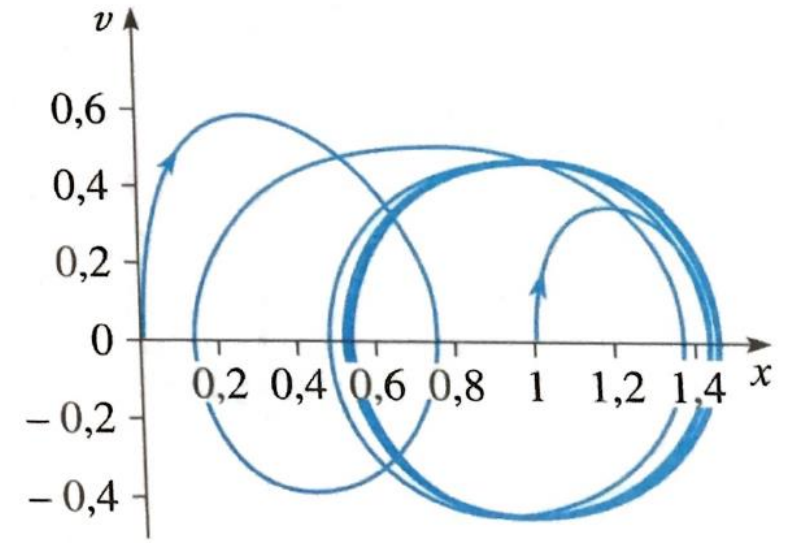
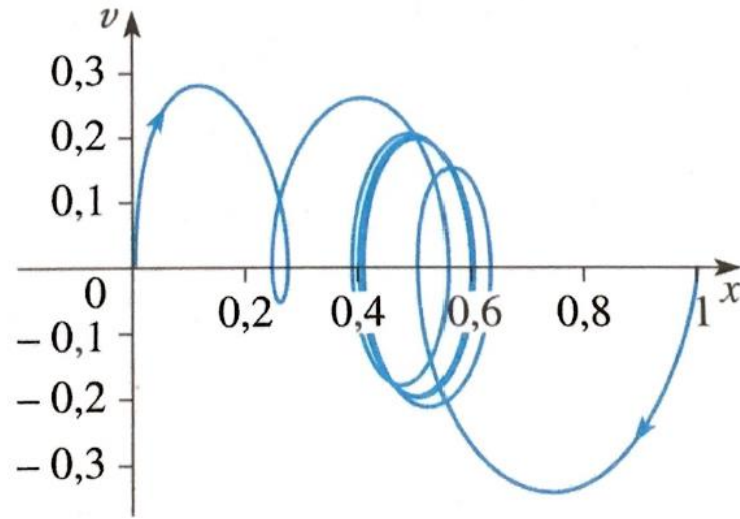
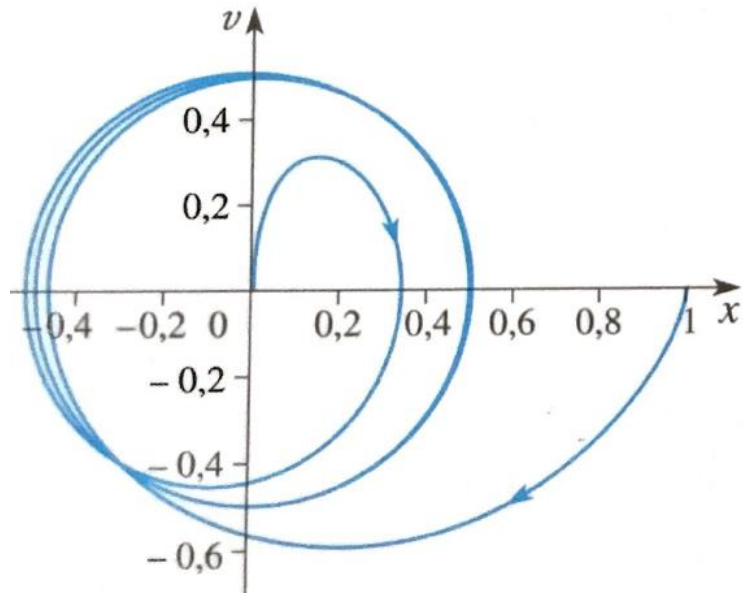


## 2. L'oscillateur amorti

### Le pendule pesant

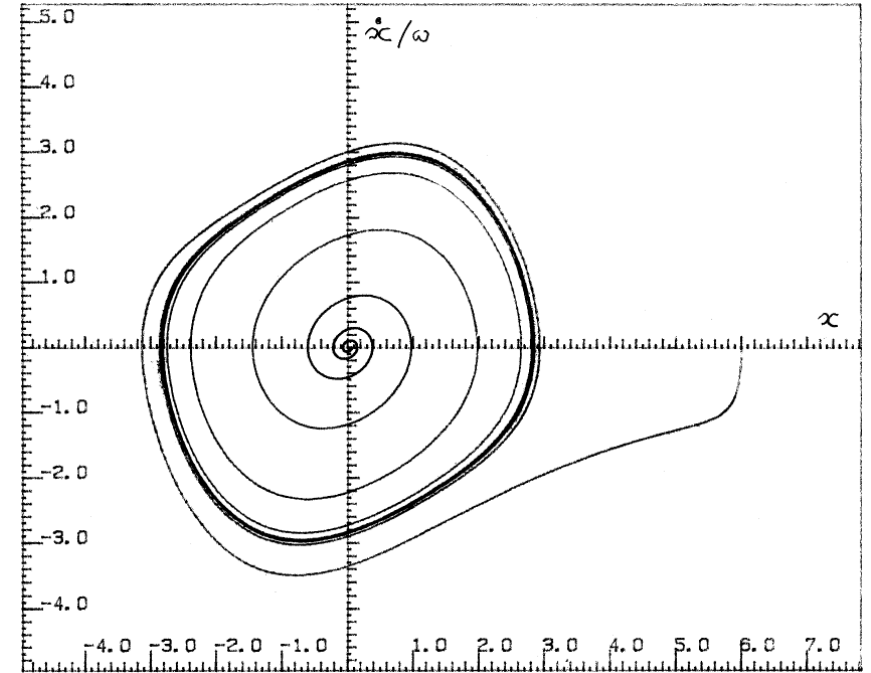
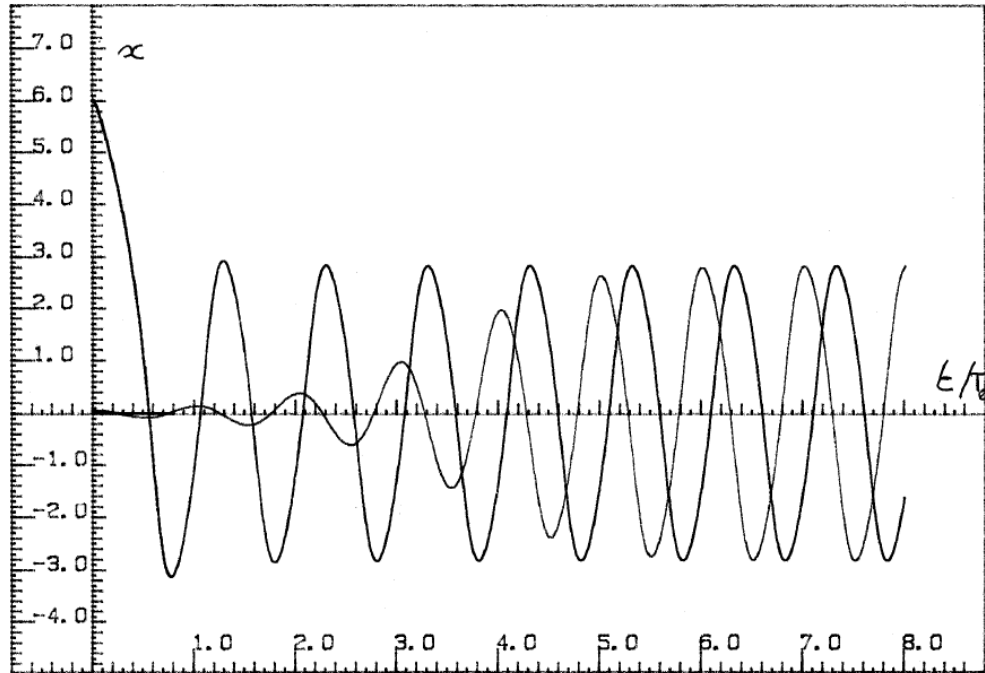


# 3. L'oscillateur forcé



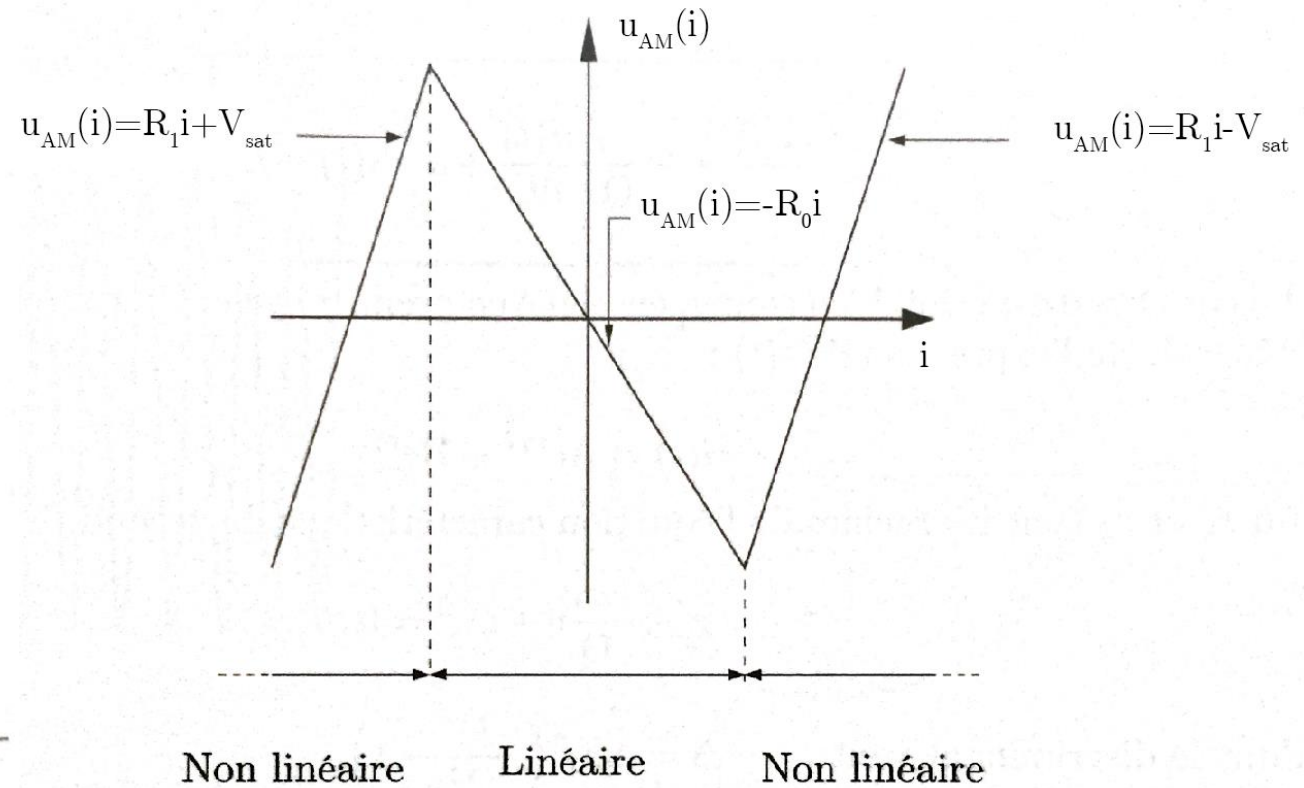
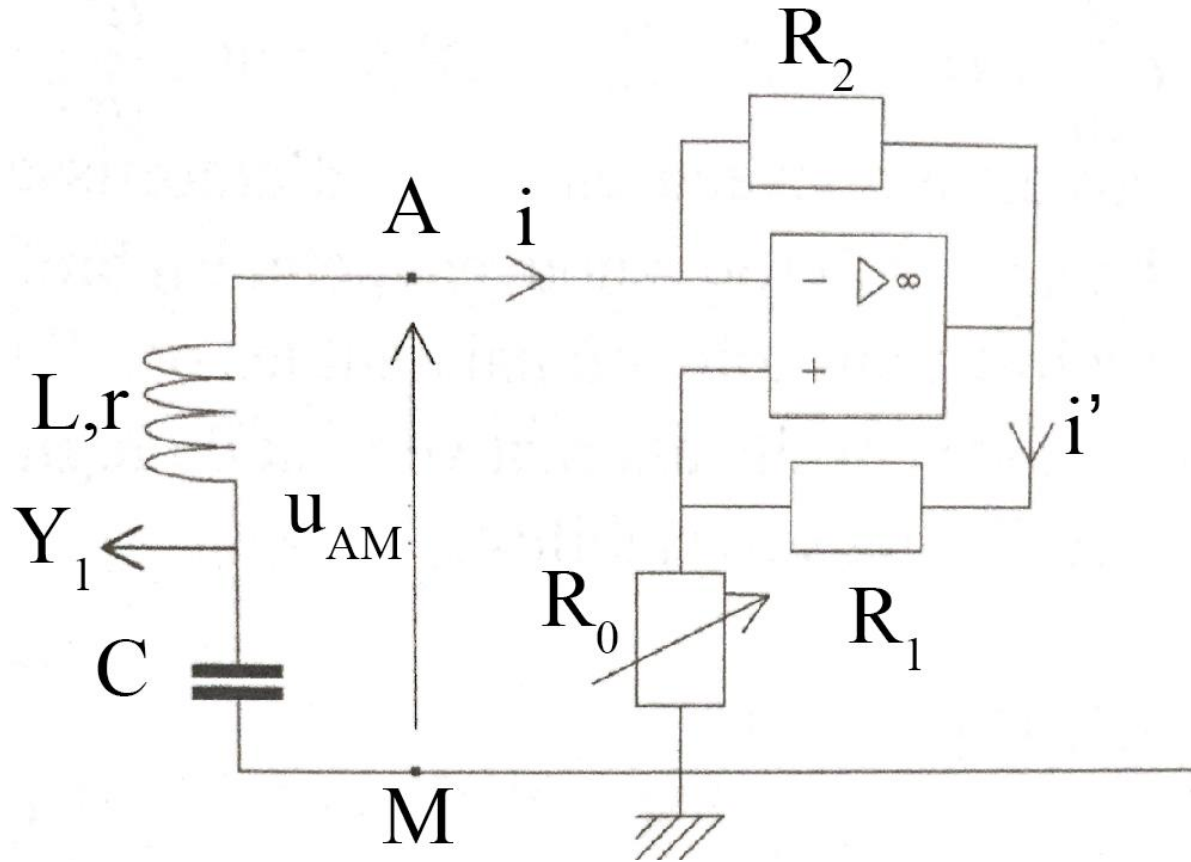


# 4. L'oscillateur auto-entretenu Le modèle de Van der Pol



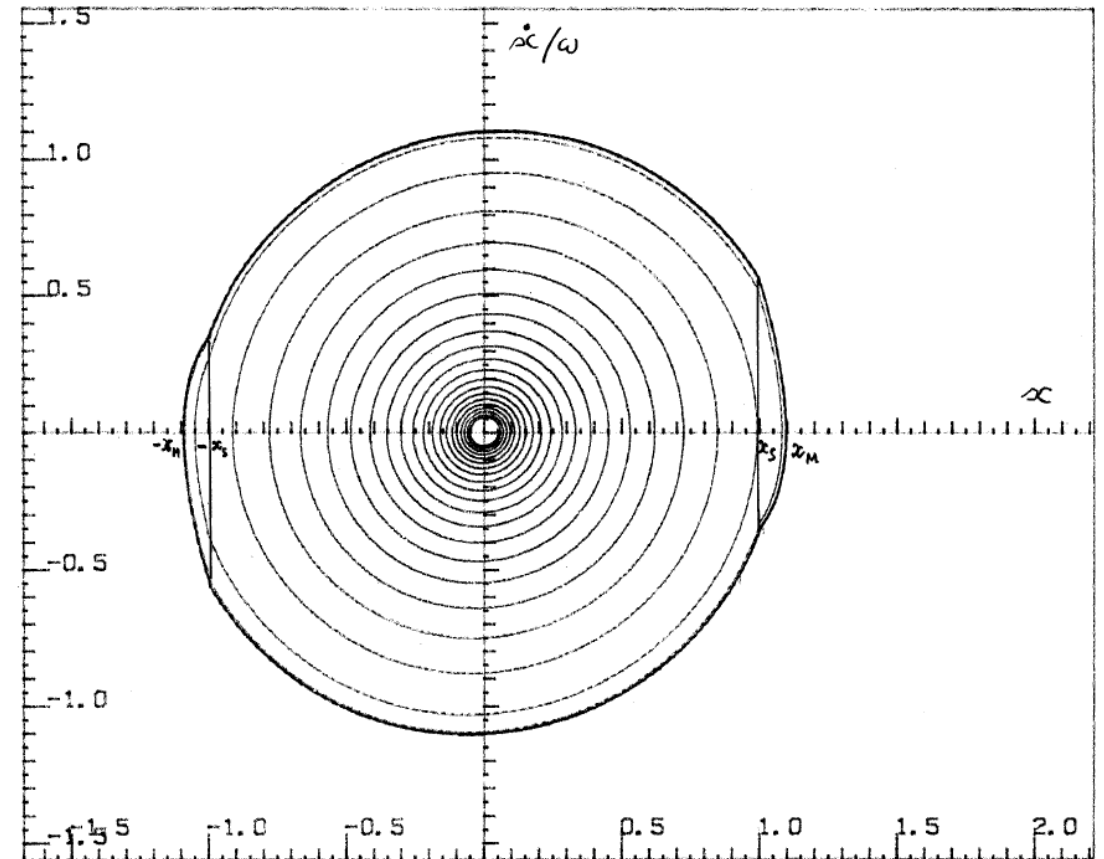
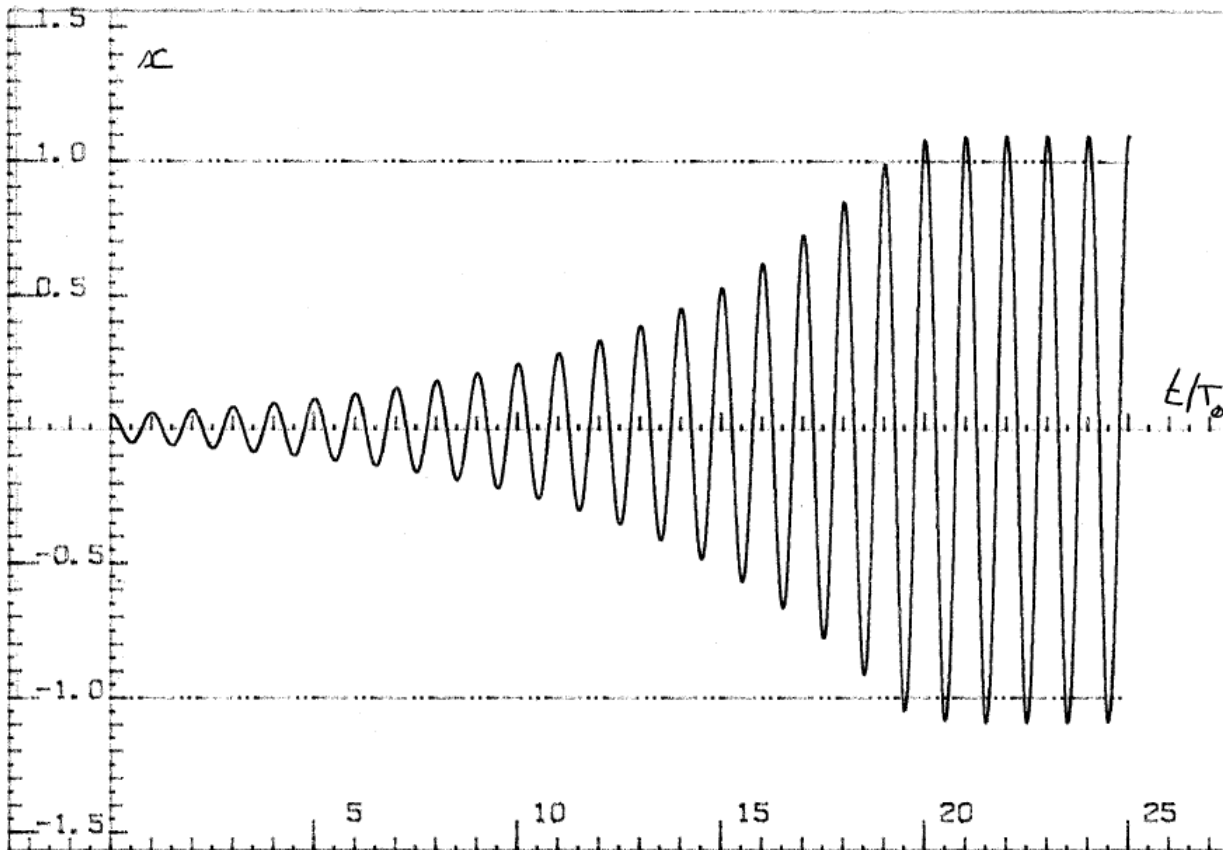
# 4. L'oscillateur auto-entretenu

## L'oscillateur à résistance négative



# 4. L'oscillateur auto-entretenu L'oscillateur à résistance négative

$$Q = -20 - \tau = 0.2$$



# 4. L'oscillateur auto-entretenu L'oscillateur à résistance négative

$$Q = -4 - \tau = 0.2$$

